

# **Mini-Course 1, Module 2**

# **Markov Decision Processes**

CMPUT 397  
Fall 2020

# Reminders: Sept 14, 2019

- Schedule with deadlines on github pages (<https://marthawhite.github.io/r/course/schedule.html>)
- **Some confusion the first week.** Slido for Participation Questions, naming C1M1 for Bandits
- **We are making best 10 of 11 for Graded Assignments (one freebie)**
- Graded Assessment for Course 1, Module 2 (3 MDPs) due **this Friday**
- **Peer-review for Course 1, Module 2 (3 MDPs) due this Sunday**
- Any questions about admin?

# **Review of Course 1, Module 2**

# Video 1: Markov Decision Processes

- Discussed the MDP formalism: states, actions, time steps, rewards, agents, environments
- Goals:
  - Understand **Markov Decision Processes**, or **MDPs**; and
  - describe how the **dynamics of an MDP** are defined

# Video 2: Examples of MDPs

- Discussed several sample problems and how they can be expressed in the language of MDPs
- Goals:
  - Gain experience **formalizing** decision-making problems as MDPs
  - Appreciate the **flexibility** of the MDP formalism

# Video 3: The Goal of Reinforcement Learning

- Discussed the goal of an RL agent, and how that relates to future reward
- Goals:
  - Describe how **rewards** relate to the **goal of an agent**, and
  - Identify **episodic tasks**

# The Reward Hypothesis

- "That all of what we mean by goals and purposes can be well thought of as the maximization of the expected value of the cumulative sum of a received scalar signal (called reward)."

# Video 4: Continuing Tasks

- Discussed why continuing tasks are special and how to define the return for continuing tasks
- Goals:
  - Differentiate between **episodic** and **continuing** tasks
  - Formulate **returns** for continuing tasks using **discounting**; and
  - Describe how **returns at successive** time steps are related to each other.



# Video 5: Examples of Episodic Tasks and Continuing Tasks

- Discussed several examples of continuing tasks, and how to formulate them as MDPs.
- **Goal:** Understand when to formalize a task as episodic or continuing

# Question and Answer

- Let's discuss a few questions from Slido
  - I will post the question I am answering in Zoom chat, labeled [Slido Q]
- Also feel free to post any questions in the Zoom chat
- I will answer these using a Whiteboard (my iPad)

# Worksheet Question 1

Suppose  $\gamma = 0.9$  and the reward sequence is  $R_1 = 2, R_2 = -2, R_3 = 0$  followed by an infinite sequence of 7s. What are  $G_1$  and  $G_0$ ?

# Worksheet Question 2

(Exercise 2.2 from S&B 2nd edition) Consider a  $k$ -armed bandit problem with  $k = 4$  actions, denoted 1, 2, 3, and 4. Consider applying to this problem a bandit algorithm using  $\epsilon$ -greedy action selection, sample-average action-value estimates, and initial estimates of  $Q_1(a) = 0$ , for all  $a$ . Suppose the initial sequence of actions and rewards is  $A_1 = 1, R_1 = 1, A_2 = 2, R_2 = 1, A_3 = 2, R_3 = 2, A_4 = 2, R_4 = 2, A_5 = 3, R_5 = 0$ . On some of these time steps the  $\epsilon$  case may have occurred, causing an action to be selected at random. On which time steps did this definitely occur? On which time steps could this possibly have occurred?

# Worksheet Question 4

Prove that the discounted sum of rewards is always finite, if the rewards are bounded:  $|R_{t+1}| \leq R_{\max}$  for all  $t$  for some finite  $R_{\max} > 0$ .

$$\left| \sum_{i=0}^{\infty} \gamma^i R_{t+1+i} \right| < \infty \quad \text{for } \gamma \in [0, 1)$$

Hint: Recall that  $|a + b| < |a| + |b|$ .